



# High dynamic range in VR

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These slides are a part of the tutorial

*Cutting-edge VR/AR Display Technologies (Gaze-, Accommodation-, Motion-aware and HDR-enabled)*

Presented at IEEE VR in Reutlingen on the 18<sup>th</sup> of March 2018

The latest version of the slides and the slides for the remaining part of the tutorial can be found at:

<https://vrdisplays.github.io/ieeivr2018/>

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# HDR & VR ?

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- ▶ Do we have HDR VR headsets?



<http://www.oculusvr.com/>



- ▶ OLED contrast 1,000,000:1

# ToC & Benefits

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- ▶ HDR in a nutshell
- ▶ Display technologies in VR
- ▶ Perception & image quality

# Dynamic range



Luminance  
↓  
 $\frac{\max L}{\min L}$   
↑  
(for SNR > 3)

# Dynamic range (contrast)

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- ▶ As ratio:

$$C = \frac{L_{\max}}{L_{\min}}$$

- ▶ Usually written as C:1, for example 1000:1.

- ▶ As “orders of magnitude”  
or log10 units:

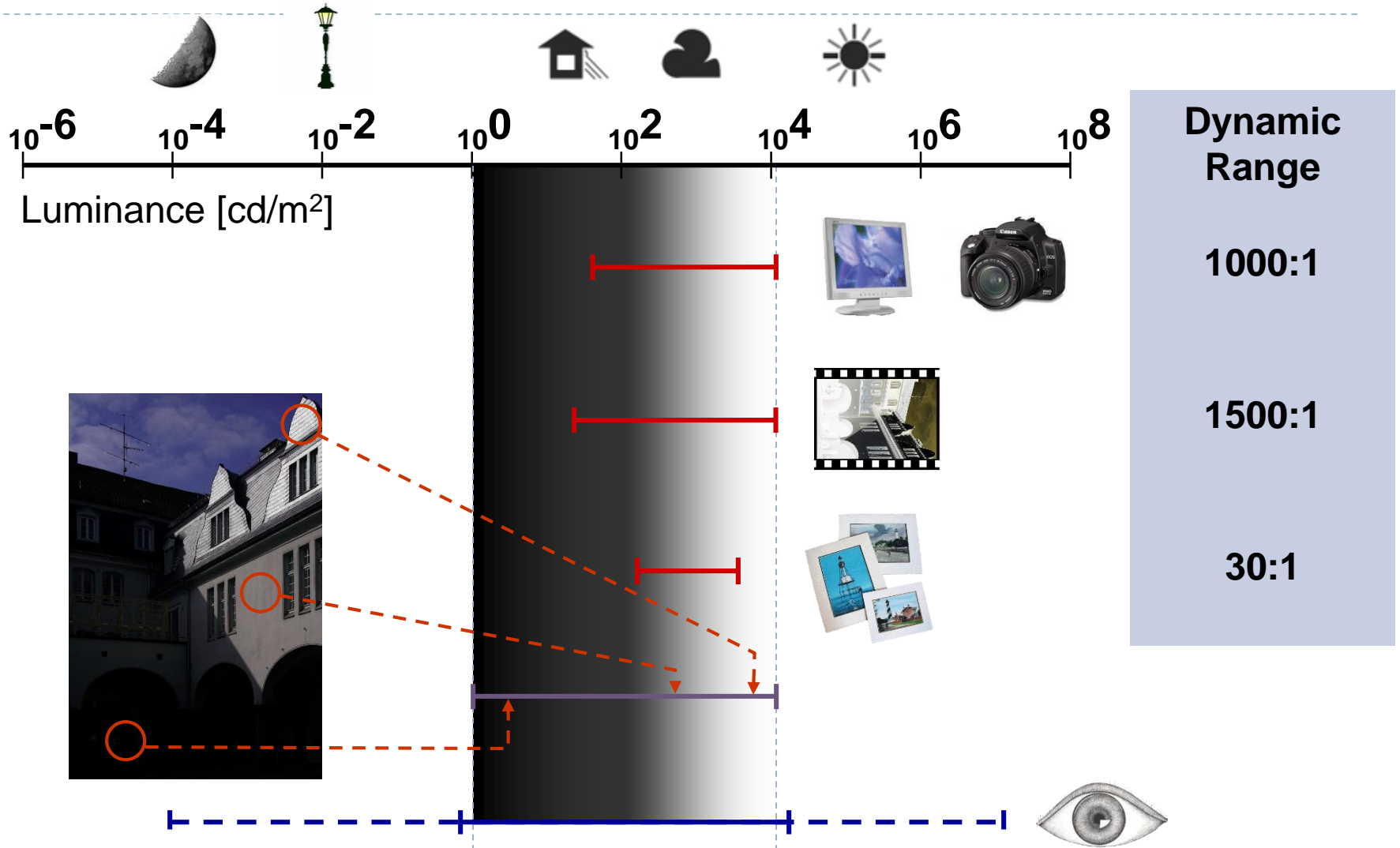
$$C_{10} = \log_{10} \frac{L_{\max}}{L_{\min}}$$

- ▶ As stops:

$$C_2 = \log_2 \frac{L_{\max}}{L_{\min}}$$

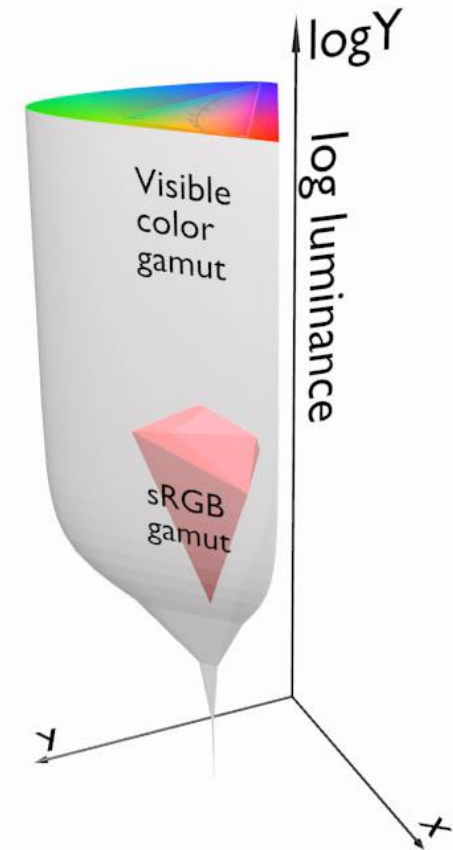
One stop is doubling  
of halving the amount of light

# High dynamic range (HDR)



# Visible colour gamut

- ▶ The eye can perceive more colours and brightness levels than
  - ▶ a display can produce
  - ▶ a JPEG file can store
- ▶ The premise of HDR:
  - ▶ Visual perception and not the technology should define accuracy and the range of colours
  - ▶ The current standards not fully follow to this principle





# Luminance

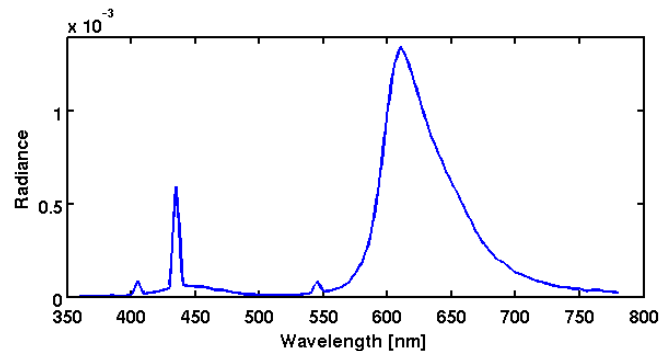
- ▶ Luminance – how bright the surface will appear regardless of its colour. Units:  $\text{cd}/\text{m}^2$

Luminance

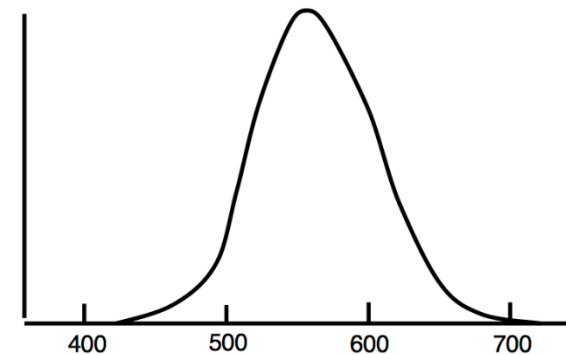
$$L_V = \int_{350}^{700} kL(\lambda)V(\lambda)d\lambda$$

$$k = \frac{1}{683.002}$$

Light spectrum (radiance)



Luminous efficiency function (weighting)



# Luminance and Luma

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## ▶ Luminance

- ▶ Photometric quantity defined by the spectral luminous efficiency function
- ▶  $L \approx 0.2126 R + 0.7152 G + 0.0722 B$
- ▶ Units:  $\text{cd}/\text{m}^2$

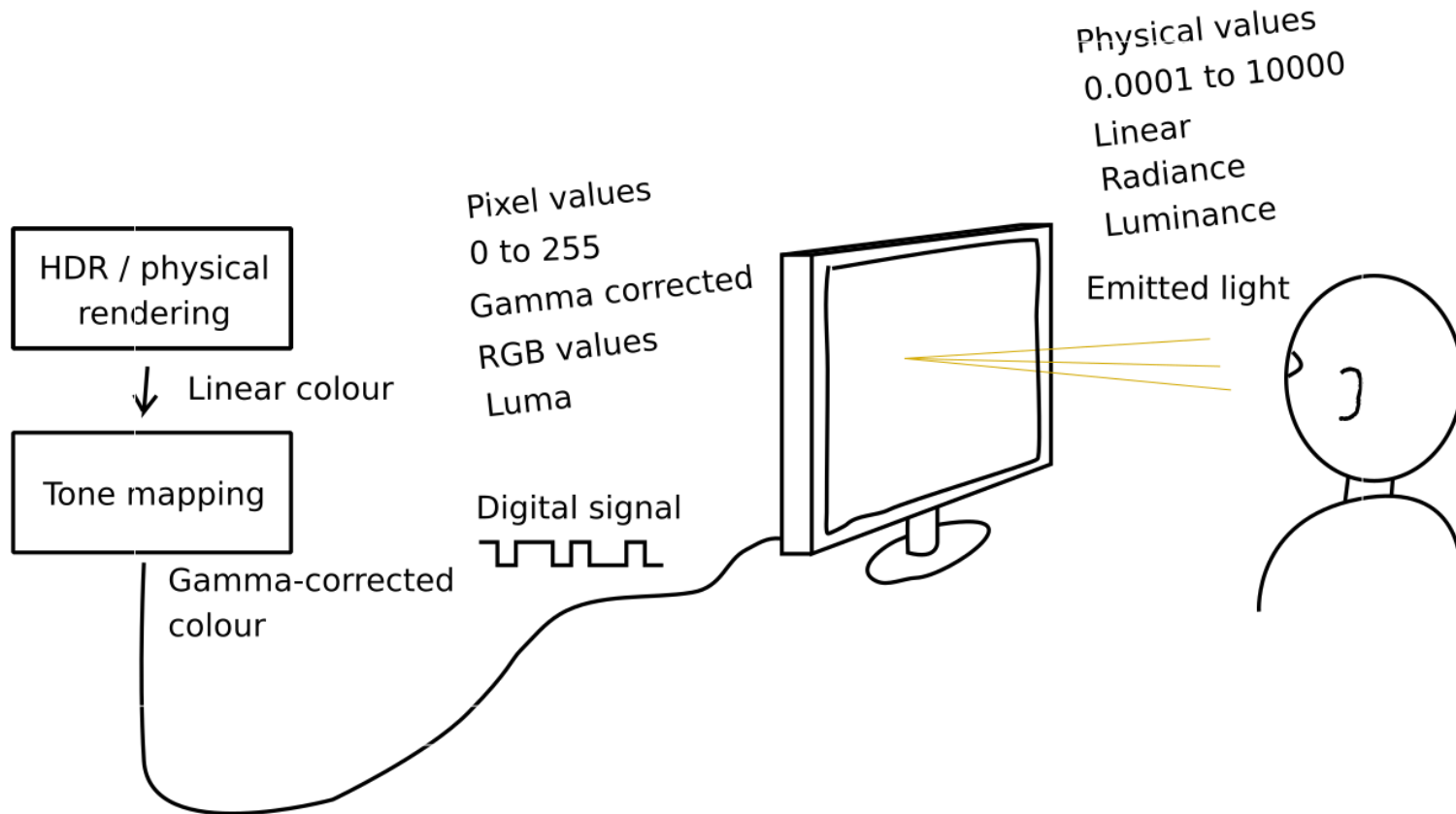
## ▶ Luma

- ▶ Gray-scale value computed from LDR (gamma corrected) image
- ▶  $Y = 0.2126 R' + 0.7152 G' + 0.0722 B'$
- ▶  $R'$  – prime denotes gamma correction

$$R' = R^{1/g}$$

## ▶ Unitless

# Linear vs. gamma-corrected values



# Sensitivity to luminance

- ▶ Weber-law – the just-noticeable difference is proportional to the magnitude of a stimulus



Ernst Heinrich Weber  
[From wikipedia]

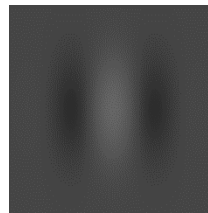
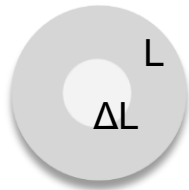
The smallest detectable luminance difference

Background (adapting) luminance

$$\frac{\Delta L}{L} = k$$

Constant

Typical stimuli:



# Consequence of the Weber-law

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- ▶ Smallest detectable difference in luminance

$$\frac{\Delta L}{L} = k$$

For k=1%

L	$\Delta L$
100 cd/m <sup>2</sup>	1 cd/m <sup>2</sup>
1 cd/m <sup>2</sup>	0.01 cd/m <sup>2</sup>

- ▶ Adding or subtracting luminance will have different visual impact depending on the background luminance
- ▶ Unlike LDR luma values, luminance values are **not** perceptually uniform!

# How to make luminance (more) perceptually uniform?

- ▶ Using “Fechnerian” integration

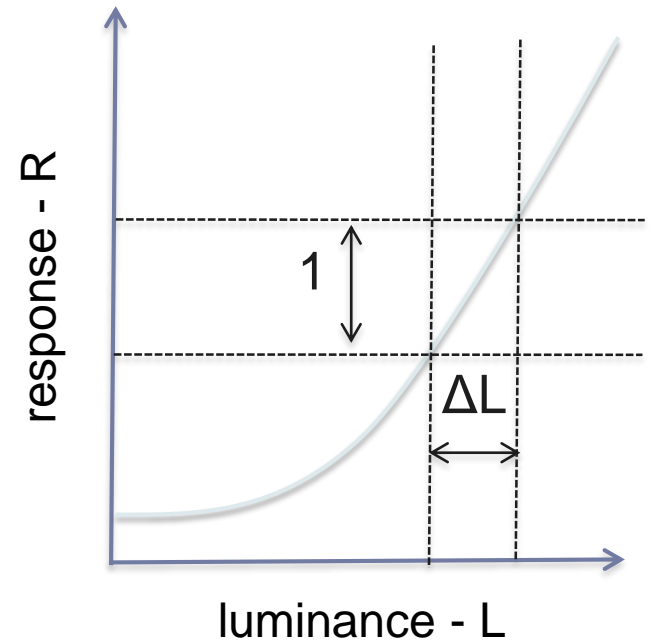
$$\frac{dR}{dl}(L) = \frac{1}{\Delta L(L)}$$

Derivative of response

Detection threshold

Luminance transducer:

$$R(L) = \int_0^L \frac{1}{\Delta L(l)} dl$$



# Assuming the Weber law

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$$\frac{\Delta L}{L} = k,$$

- ▶ and given the luminance transducer

$$R(L) = \int_0^L \frac{1}{\Delta L(l)} dl$$

- ▶ the response of the visual system to light is:

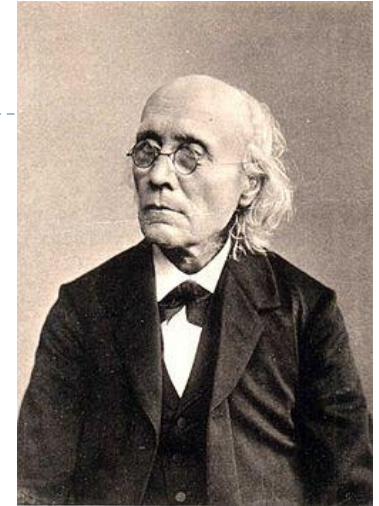
$$R(L) = \int \frac{1}{kL} dL = \frac{1}{k} \ln(L) + k_1$$

# Fechner law

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$$R(L) = a \ln(L)$$

- ▶ Response of the visual system to luminance is **approximately** logarithmic
- ▶ The values of HDR pixel values are much more intuitive when they are plotted / considered / processed in the logarithmic domain

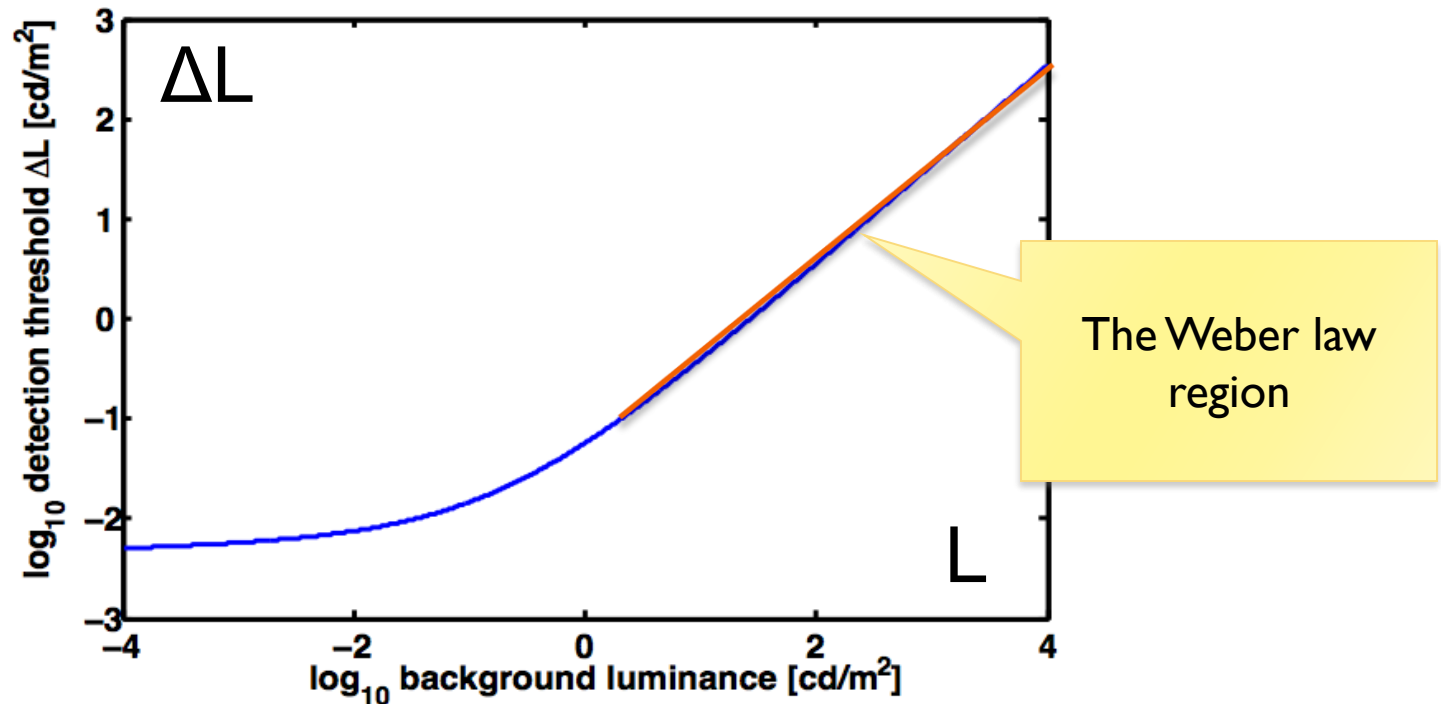


Gustav Fechner  
[From Wikipedia]



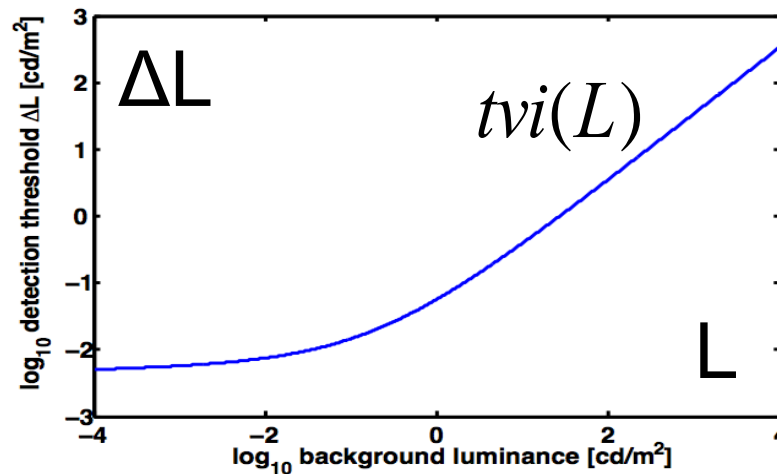
# But...the Fechner law does not hold for the full luminance range

- ▶ Because the Weber law does not hold either
- ▶ Threshold vs. intensity function:



# Weber-law revisited

- ▶ If we allow detection threshold to vary with luminance according to the t.v.i. function:



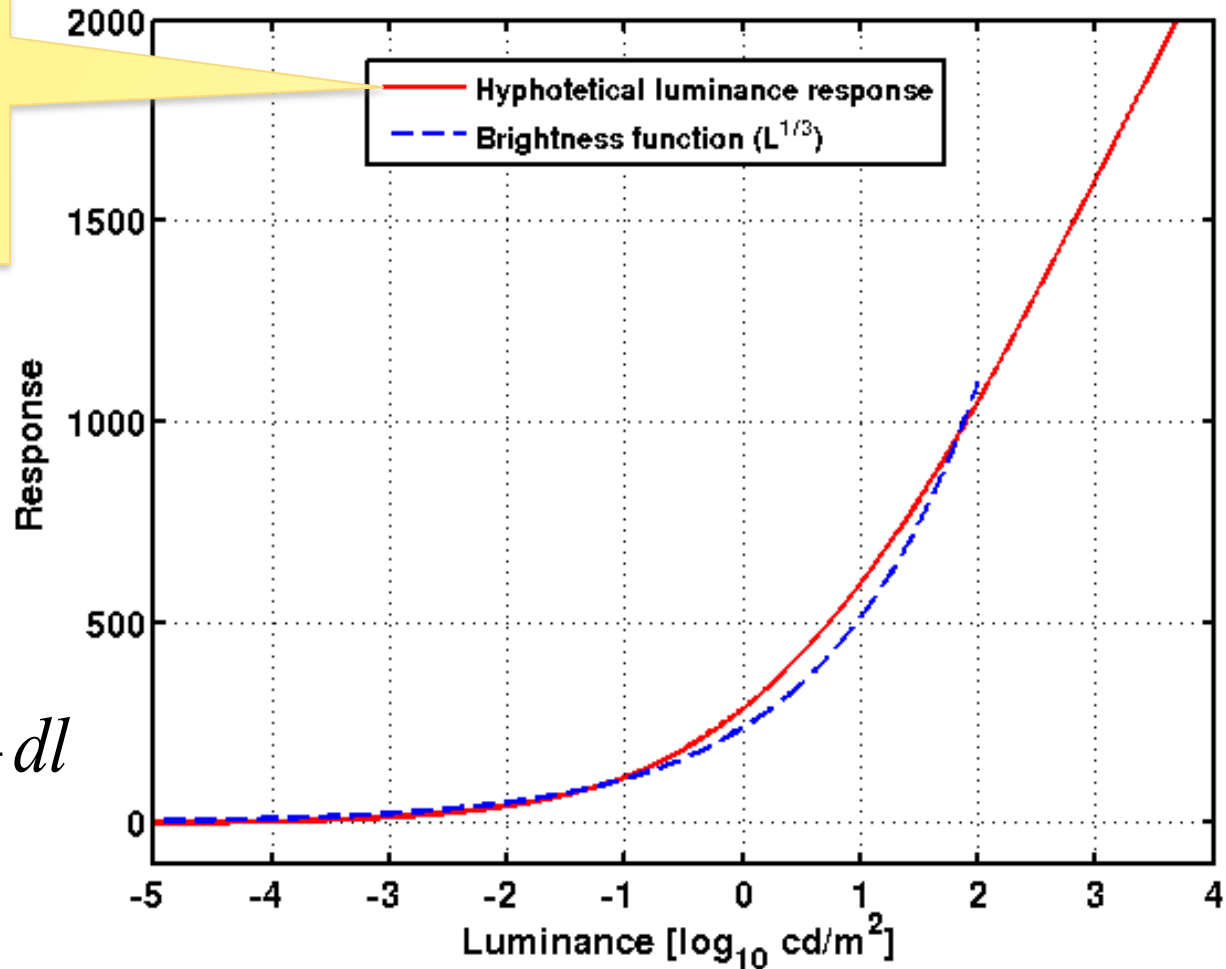
- ▶ we can get more accurate estimate of the “response”:

$$R(L) = \int_0^L \frac{1}{tvi(l)} dl$$

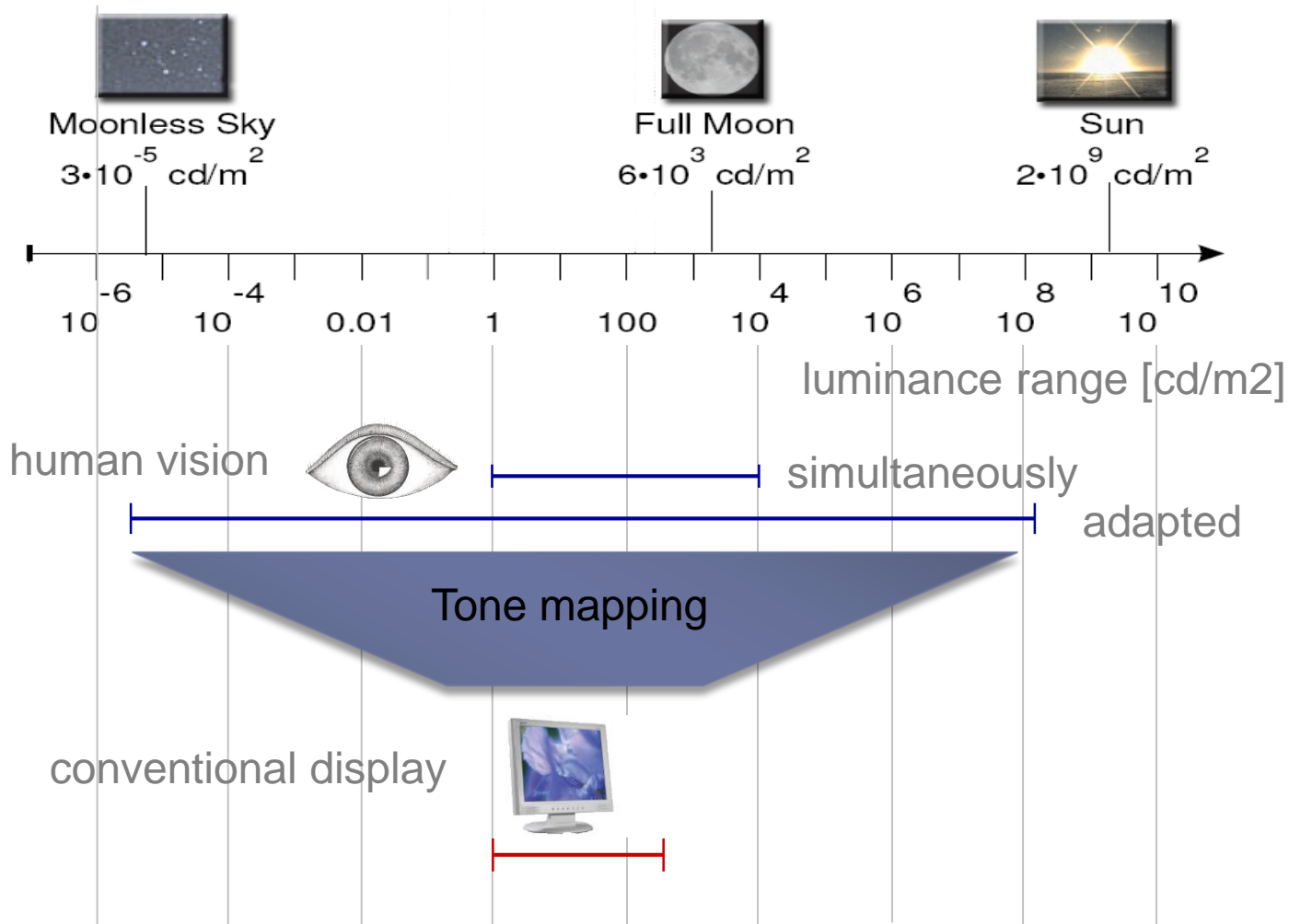
# Fechnerian integration and Stevens' law

R(L) - function derived from the t.v.i. function

$$R(L) = \int_0^L \frac{1}{tvi(l)} dl$$



# Tone-mapping problem



# Why do we need tone mapping?

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- ▶ To reduce excessive dynamic range
  - ▶ To customize the look (colour grading)
  - ▶ To simulate human vision
    - ▶ for example night vision
  - ▶ To adapt displayed images to a display and viewing conditions
  - ▶ To make rendered images look more realistic
- 
- ▶ Different tone mapping techniques achieve different goals



# Tone-mapping in rendering

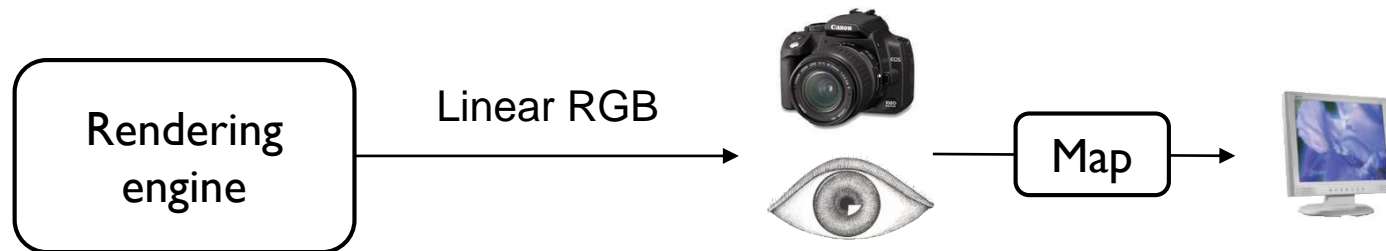
- ▶ Any physically-based rendering requires tone-mapping
- ▶ “HDR rendering” in games is pseudo-physically-based rendering
- ▶ Goal: to simulate a camera or the eye
- ▶ Greatly enhances realism

LDR illumination  
No tone-mapping

HDR illumination  
Tone-mapping



Half-Life 2: Lost coast



Simulate

# Tone-curve

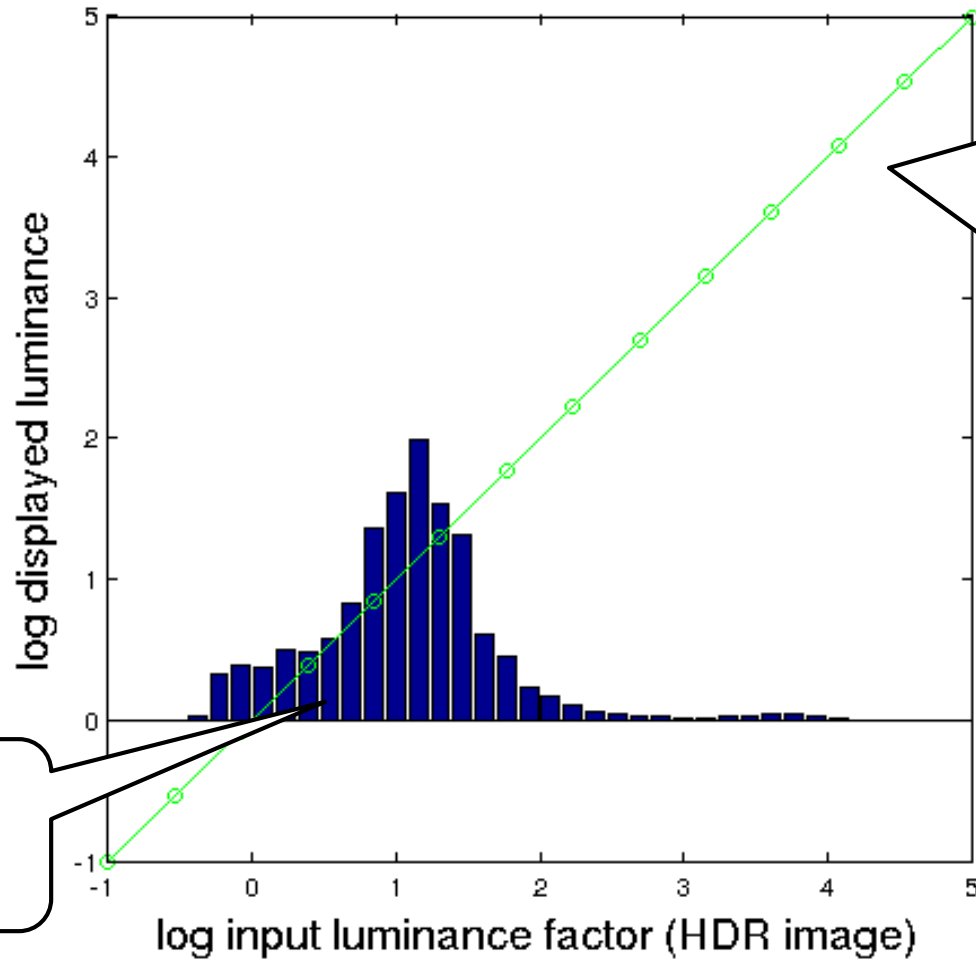
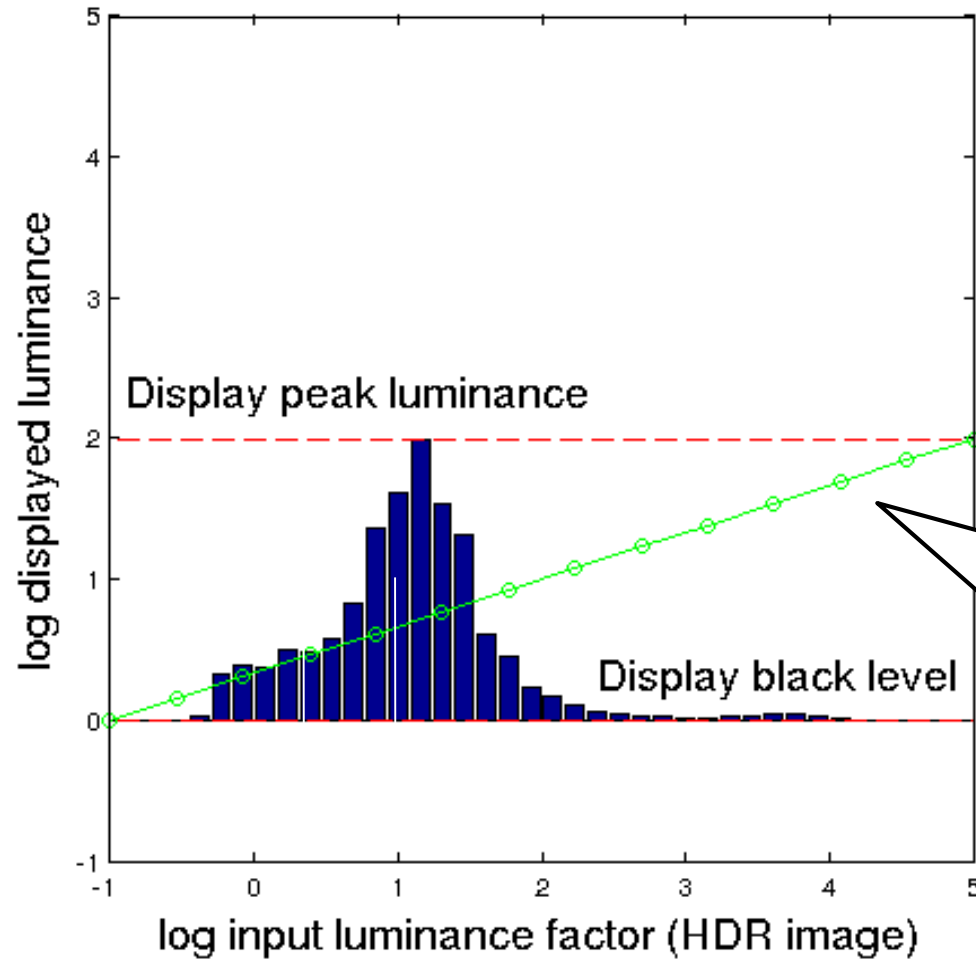


Image histogram

Best tone-mapping is the one which does not do anything, i.e. slope of the tone-mapping curves is equal to 1.

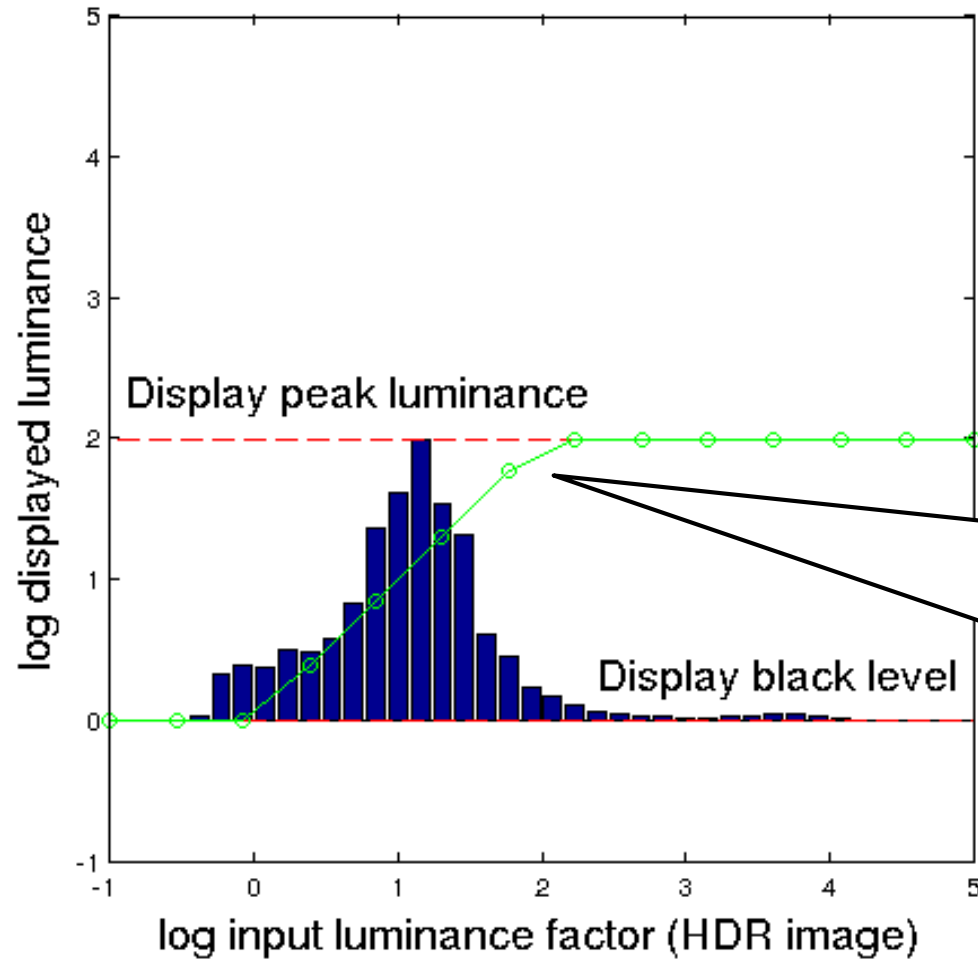
# Tone-curve



But in practice contrast (slope) must be limited due to display limitations.



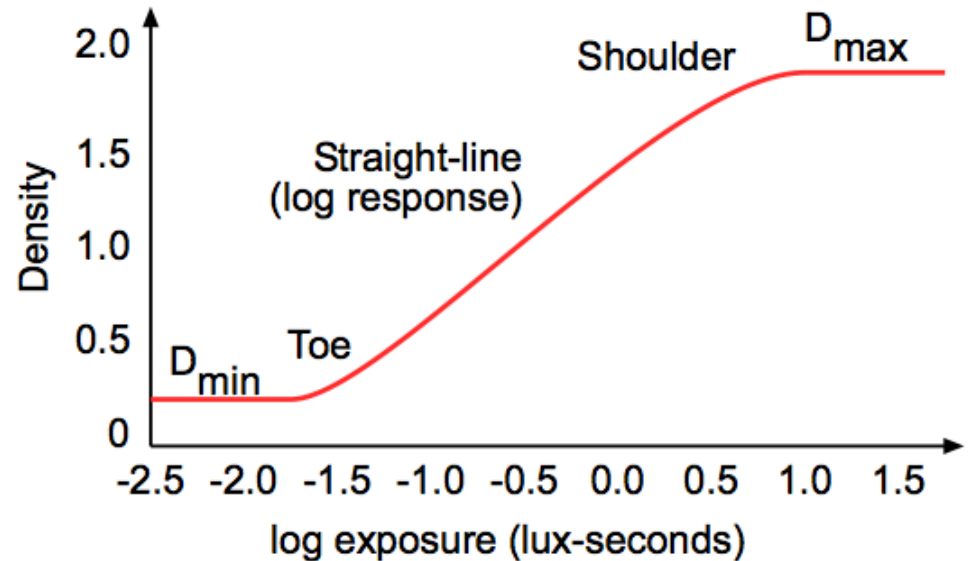
# Tone-curve



Global tone-mapping is a compromise between clipping and contrast compression.

# Sigmoidal tone-curves

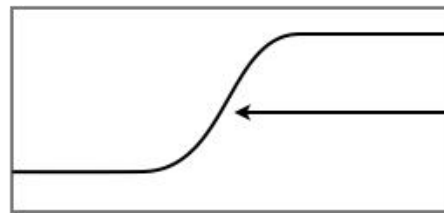
- ▶ Very common in digital cameras
  - ▶ Mimic the response of analog film
  - ▶ Analog film has been engineered over many years to produce good tone-reproduction
- ▶ Fast to compute



# Tone-curve as an optimization problem



input scene

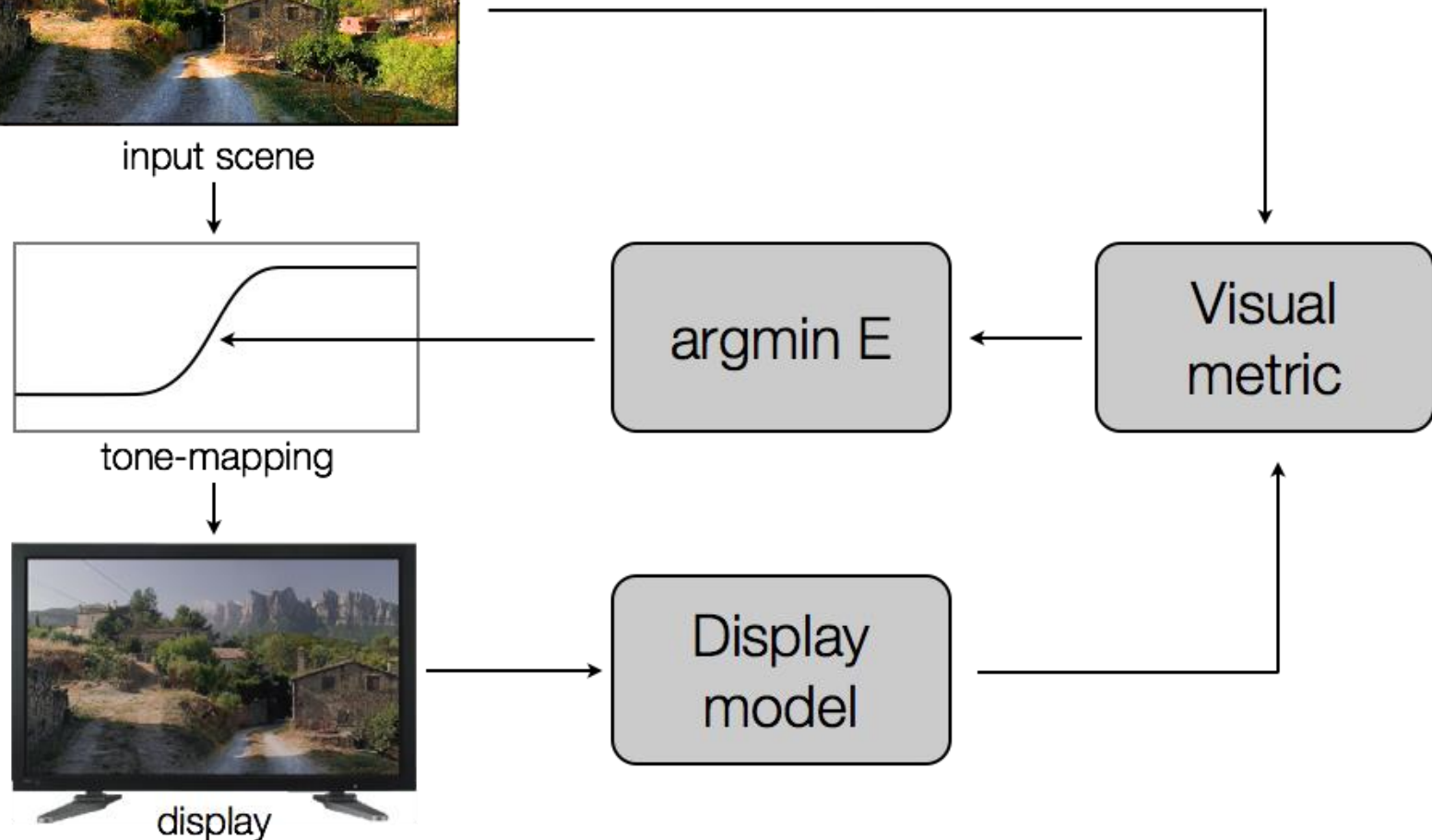


tone-mapping



display

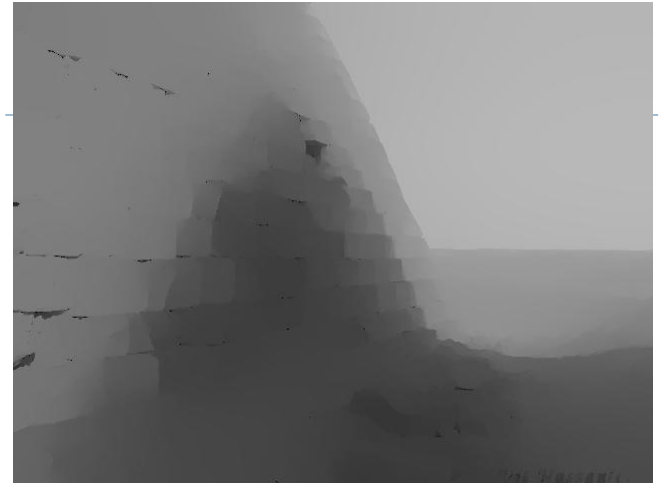
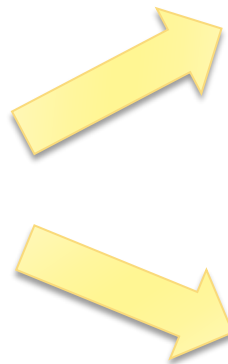
Goal: Minimize the visual difference between the input and displayed images



# Illumination & reflectance separation



Input



Illumination



Reflectance

$$Y = I \times R$$

Image

Illumination

Reflectance

# Illumination and reflectance

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## Reflectance

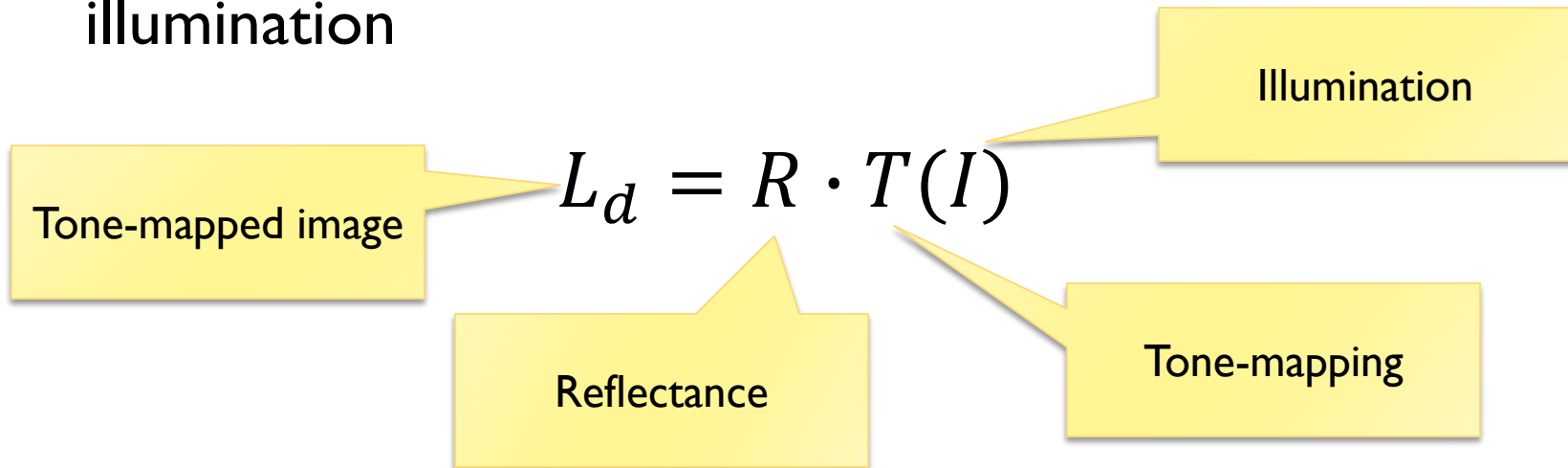
- ▶ White  $\approx 90\%$
- ▶ Black  $\approx 3\%$
- ▶ Dynamic range  $< 100:1$
- ▶ Reflectance critical for object & shape detection

## Illumination

- ▶ Sun  $\approx 10^9 \text{ cd/m}^2$
- ▶ Lowest perceivable luminance  $\approx 10^{-6} \text{ cd/m}^2$
- ▶ Dynamic range 10,000:1 or more
- ▶ Visual system partially discounts illumination

# Reflectance & Illumination TMO

- ▶ Hypothesis: *Distortions in reflectance are more apparent than the distortions in illumination*
- ▶ Tone mapping could preserve reflectance but compress illumination



- ▶ for example:

$$L_d = R \cdot (I / L_{white})^c \cdot L_{white}$$

# How to separate the two?

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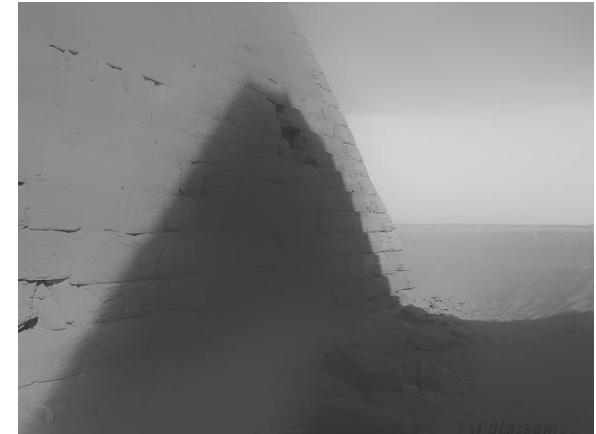
- ▶ (Incoming) illumination – slowly changing
  - ▶ except very abrupt transitions on shadow boundaries
- ▶ Reflectance – low contrast and high frequency variations



# Bilateral filter

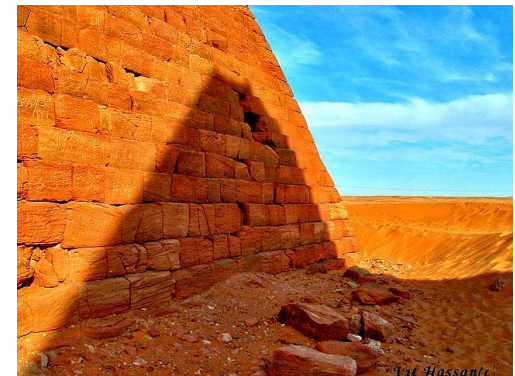
$$I_p \approx \frac{1}{k_s} \sum_{t \in \Omega} f(p-t) g(L_p - L_t) L_p$$

- ▶ Better preserves sharp edges



Tone mapping result

- ▶ Still some blurring on the edges
- ▶ Reflectance is not perfectly separated from illumination near edges





# Glare

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"Alan Wake" © Remedy Entertainment

# Glare Illusion

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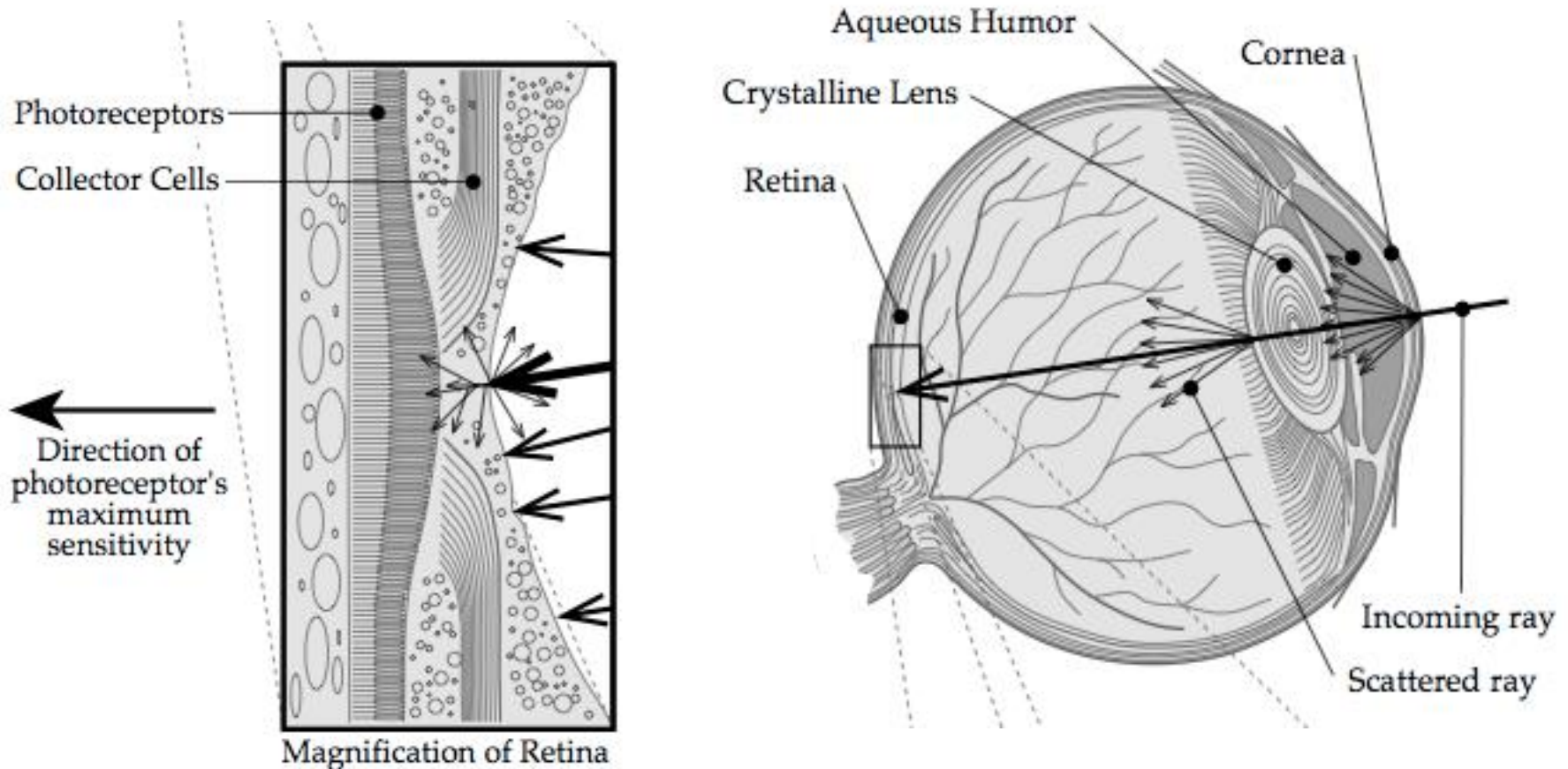
Photography



Painting

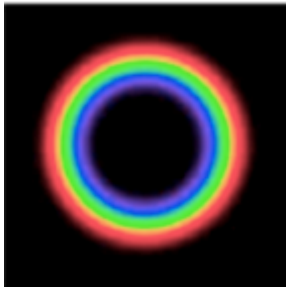


# Scattering of the light in the eye

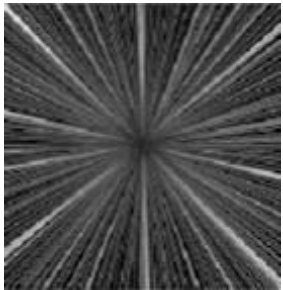


From: Sekuler, R., and Blake, R. Perception, second ed. McGraw- Hill, New York, 1990

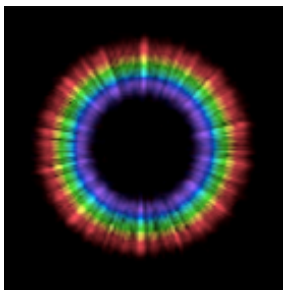
# Ciliary corona and lenticular halo



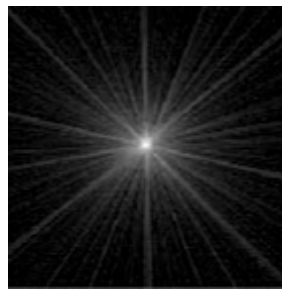
\*



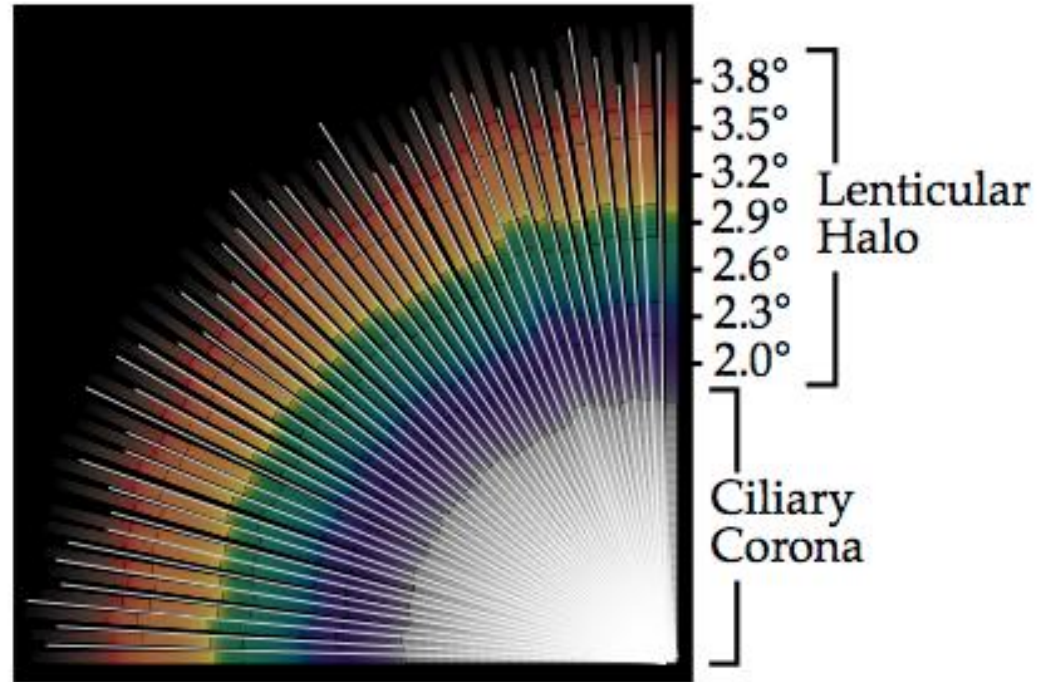
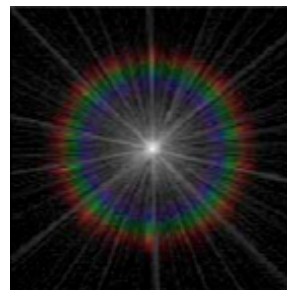
=



+



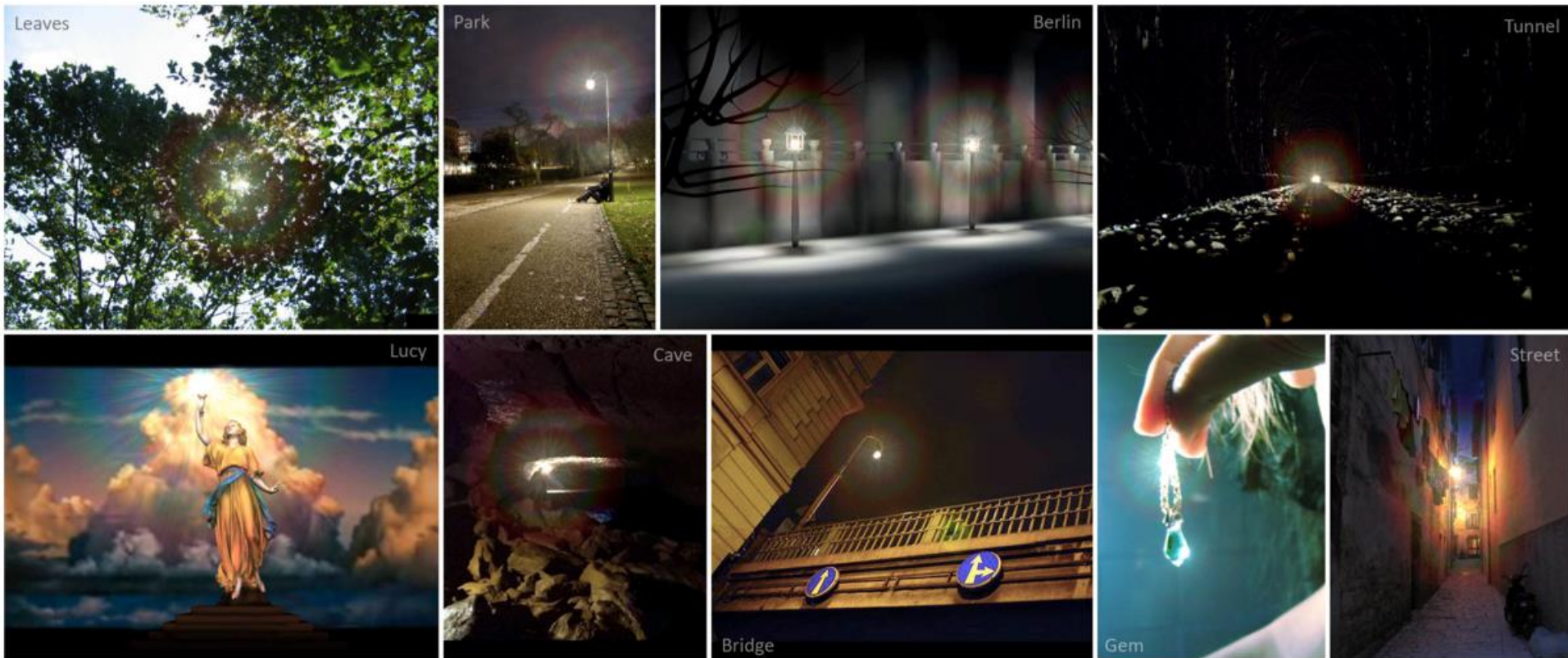
=



From: Spencer, G. et al.  
1995. Proc. of  
SIGGRAPH. (1995)

# Examples of simulated glare

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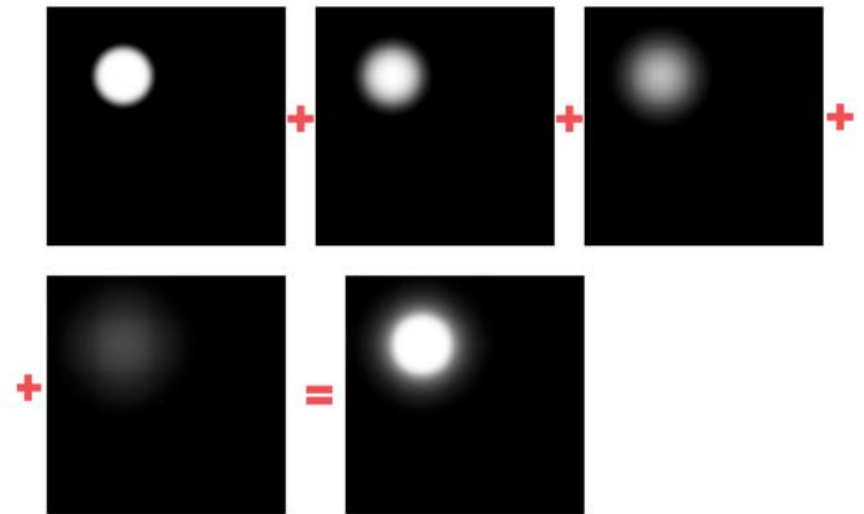


[From Ritschel et al, Eurographics 2009]

# Glare (or bloom) in games

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- ▶ Convolution with large, non-separable filters is too slow
- ▶ The effect is approximated by a combination of Gaussian filters
  - ▶ Each filter with different “sigma”
- ▶ The effect is meant to look good, not be an accurate model of light scattering
- ▶ Some games simulate camera rather than the eye









Age-adaptive night vision

# Video 4

Rivoli

Simulation of age-adaptive night vision



# ToC & Benefits

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- ▶ HDR in a nutshell
- ▶ Display technologies in VR
- ▶ Perception & image quality

# VR display technologies

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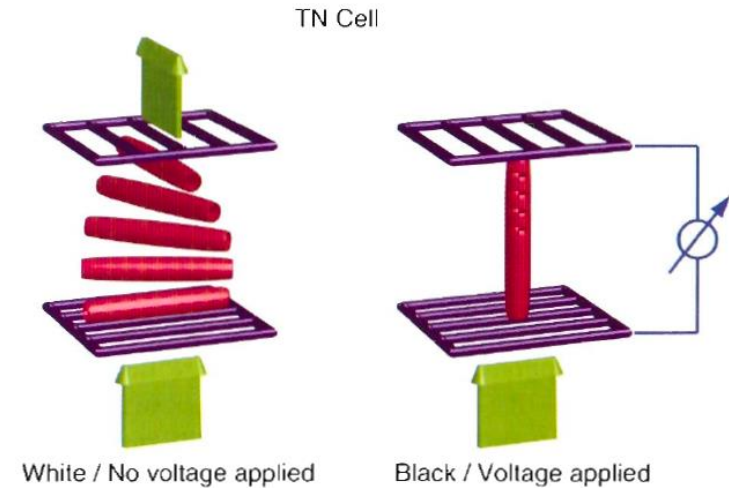
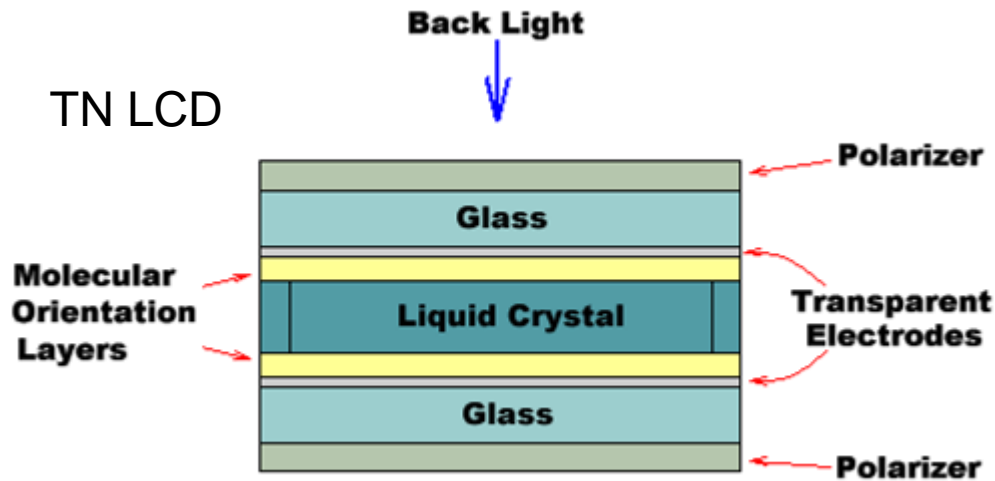
## **TFT-LCD** *TN, STN, MVA, PVA, IPS*

- ▶ Contrast: <3000:1
- ▶ Transmissive
- ▶ Complex temporal response
- ▶ Arbitrary bright
- ▶ Constant power at constant backlight

## **AMOLED**

- ▶ Contrast: >10,000:1
- ▶ Emmissive
- ▶ Rapid response
- ▶ Brightness affects longevity
- ▶ Power varies with image content

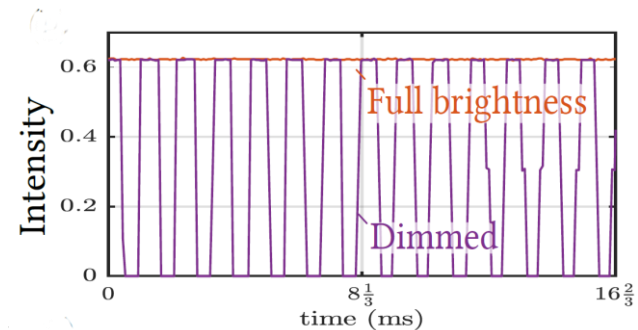
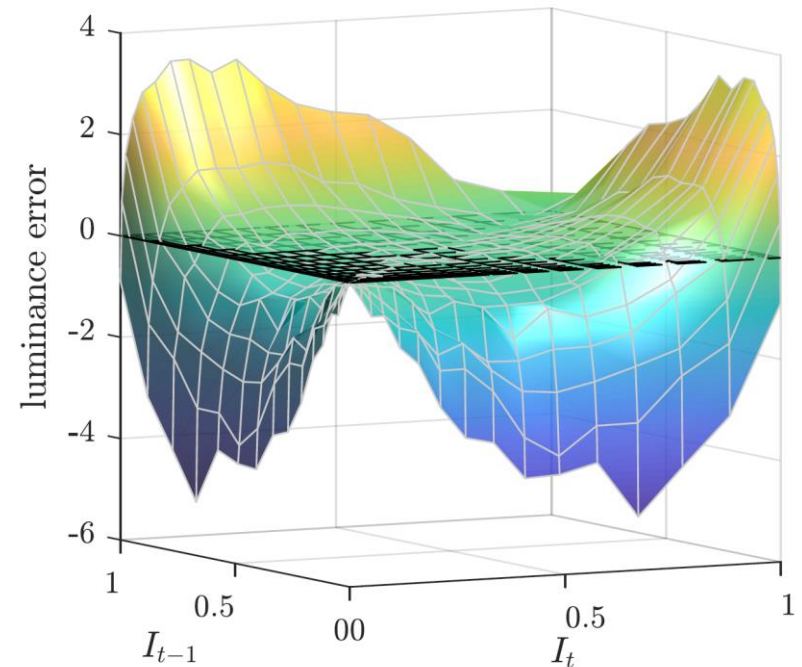
# LCD



- ▶ color may change with the viewing angle
- ▶ contrast up to 3000:1
- ▶ higher resolution results in smaller fill-factor
- ▶ color LCD transmits only up to 8% (more often close to 3-5%) light when set to full white

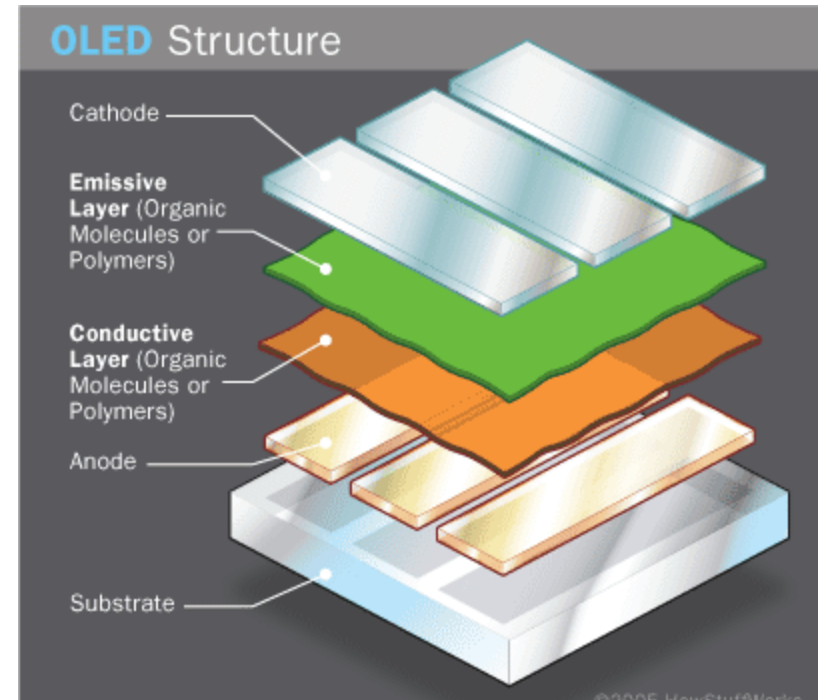
# LCD temporal response

- ▶ Experiment on an IPS LCD screen
- ▶ We rapidly switched between two intensity levels at 120Hz
- ▶ Measured luminance integrated over 1s
- ▶ The top plot shows the difference between expected ( $\frac{I_{t-1}+I_t}{2}$ ) and measured luminance
- ▶ The bottom plot: intensity measurement for the full brightness and half-brightness display settings



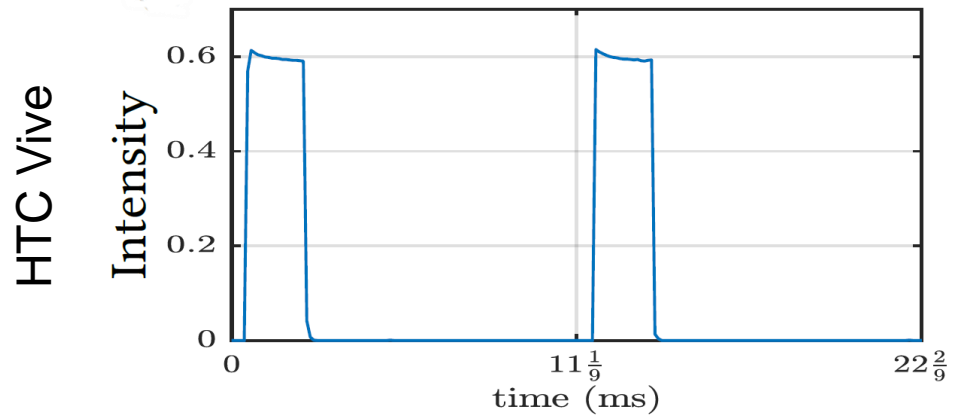
# OLED

- ▶ based on electrophosphorescence
  - ▶ large viewing angle
  - ▶ the power consumption varies with the brightness of the image
  - ▶ fast ( $< 1$  microsec)
  - ▶ arbitrary sizes
- 
- ▶ life-span is a concern
  - ▶ more difficult to produce

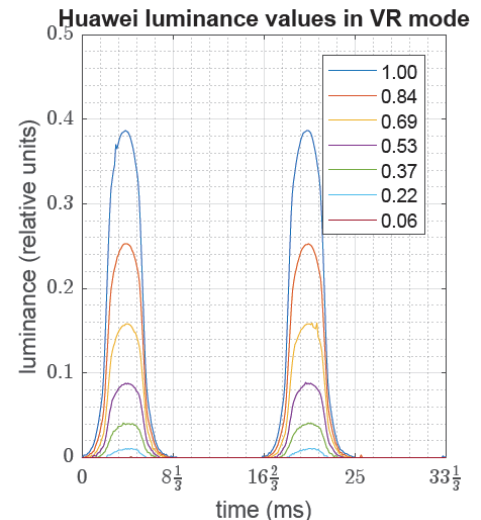
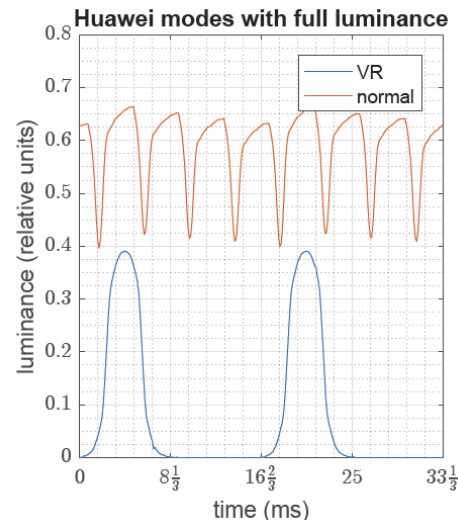


# Low persistence displays

- ▶ Most VR displays flash an image for a fraction of frame duration
- ▶ This reduces hold-type blur
- ▶ And also reduces the perceived lag of the rendering

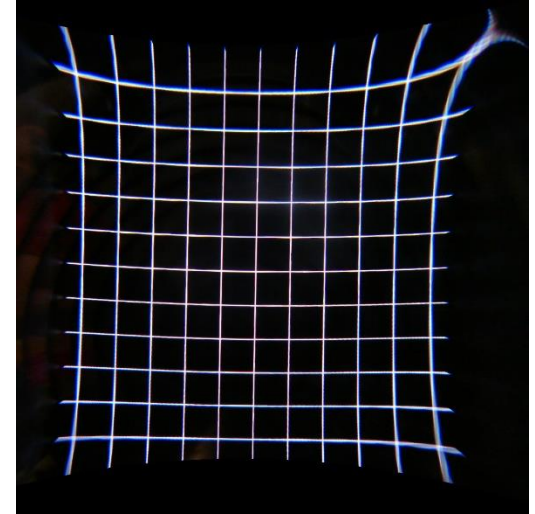


Mate 9 Pro + DayDream



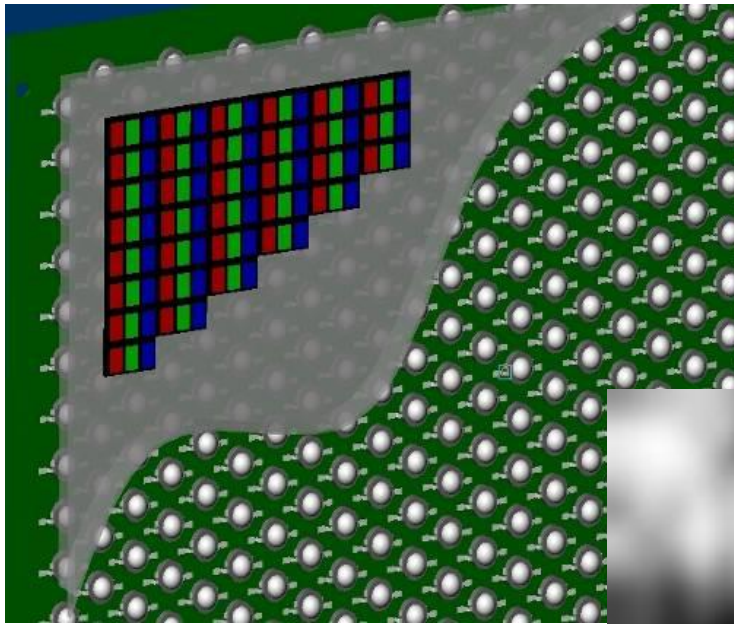
# Lens in VR displays

- ▶ **Aberrations when viewing off-center**
  - ▶ Chromatic aberration
  - ▶ Loss of resolution
  - ▶ Difficult to eliminate if the exact eye position is unknown
- ▶ **Glare**
  - ▶ Scattering of the light in the lens
  - ▶ From Fresnel fringes
  - ▶ Reduces dynamic range





# HDR Display

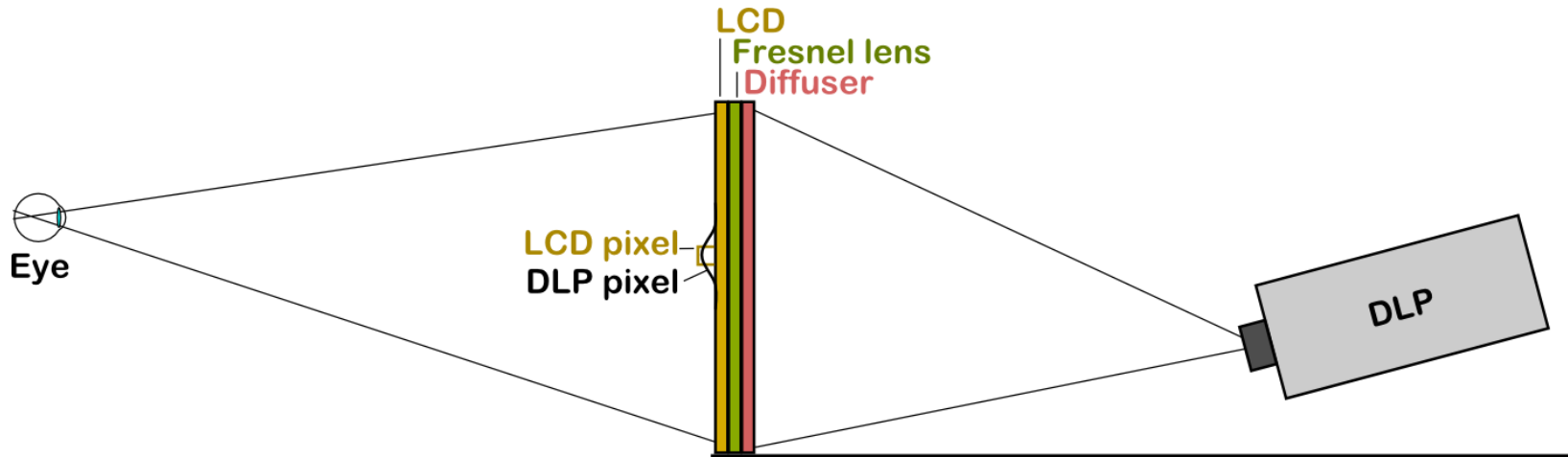


- Modulated LED array
- Conventional LCD
- Image compensation



$$\text{Low resolution LED Array} \times \text{High resolution Colour Image} = \text{High Dynamic Range Display}$$

# HDR display



Desired image

DLP blur (PSF)

$$\arg \min_{L, D} \|I - g D \circ L\|_2$$

Subject to:

$$\forall(x, y) \quad L_{min} \leq L(x, y) \leq L_{max}$$

$$\forall(x, y) \quad D_{min} \leq D(x, y) \leq D_{max}$$

DLP image

LCD image

# Resolution

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- ▶ Relevant units: pixels per visual degree [ppd]
- ▶ Nyquist frequency in cycles per degree =  $\frac{1}{2}$  of ppd
- ▶ PC & mobile resolution
  - ▶ 1981: 12" 320x200 monitor @50cm: 10.9 ppd
  - ▶ 1990: 12" 1024x768 monitor @50cm: 37 ppd
  - ▶ 2011: 3.5" 960x640 iPhone @30cm: 68 ppd
  - ▶ 2016: 31" 4K monitor @50cm: 50 ppd
  - ▶ 2018: 6" phone @30cm: 117 ppd
- ▶ VR resolution
  - ▶ 2016 HTC Vive: 10 ppd
  - ▶ 2018 HTC Vive Pro: 13 ppd

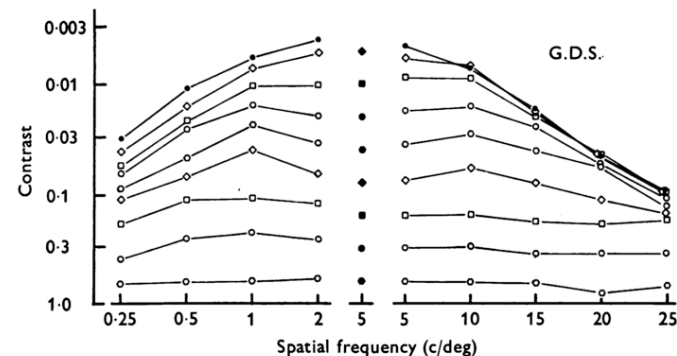
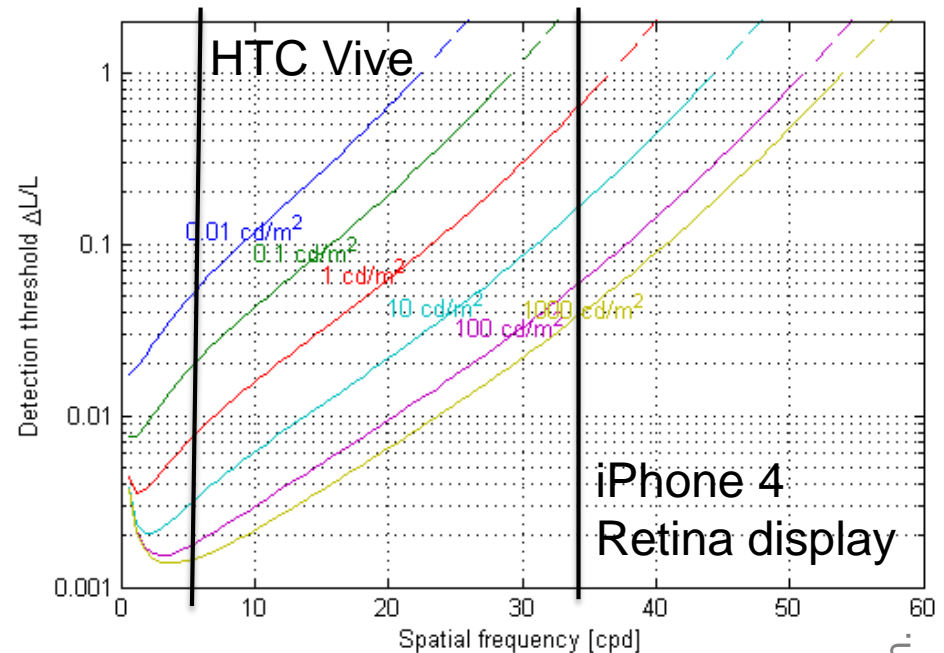
# ToC & Benefits

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- ▶ HDR in a nutshell
- ▶ Display technologies in VR
- ▶ Perception & image quality

# Contrast Sensitivity Function

- ▶ Detection of barely noticeable contrast on a uniform background
- ▶ Varies with luminance
- ▶ CSF is NOT MTF of visual system
  - ▶ Contrast constancy
  - ▶ There is little variation in magnitude of perceived contrast above the detection threshold

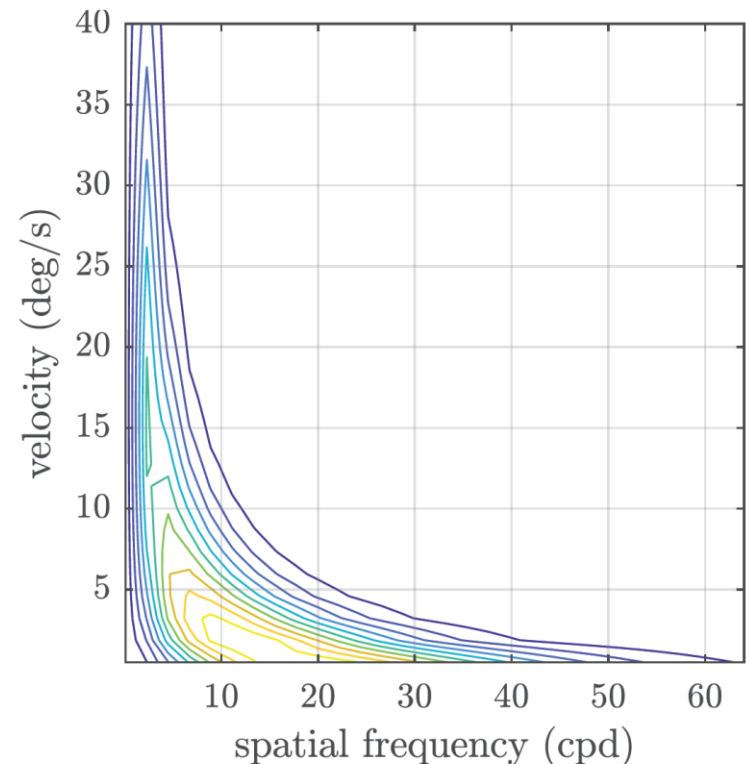


Georgeson and Sullivan.  
1975. J. Physio

# Retinal velocity

- ▶ Sensitivity drops rapidly once images start to move
- ▶ The eye tracks moving objects
  - ▶ Smooth Pursuit Eye Motion (SPEM)
  - ▶ Stabilizes images on the retina
  - ▶ But tracking is not perfect
- ▶ Loss of sensitivity mostly caused by imperfect SPEM
  - ▶ SPEM worse at high velocities
- ▶ Motion sharpening
  - ▶ Relatively small effect

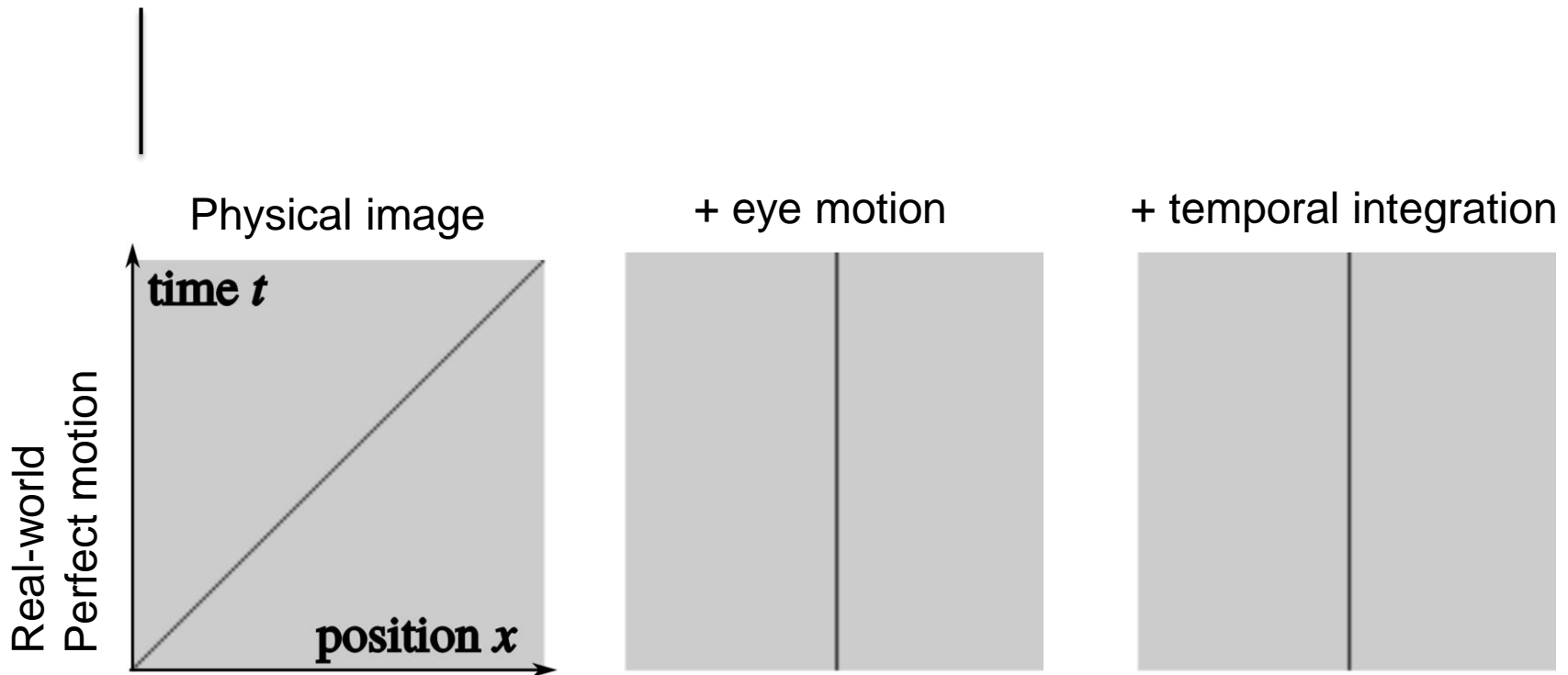
Spatio-velocity contrast sensitivity



Kelly's model [1979]

# Hold-on blur

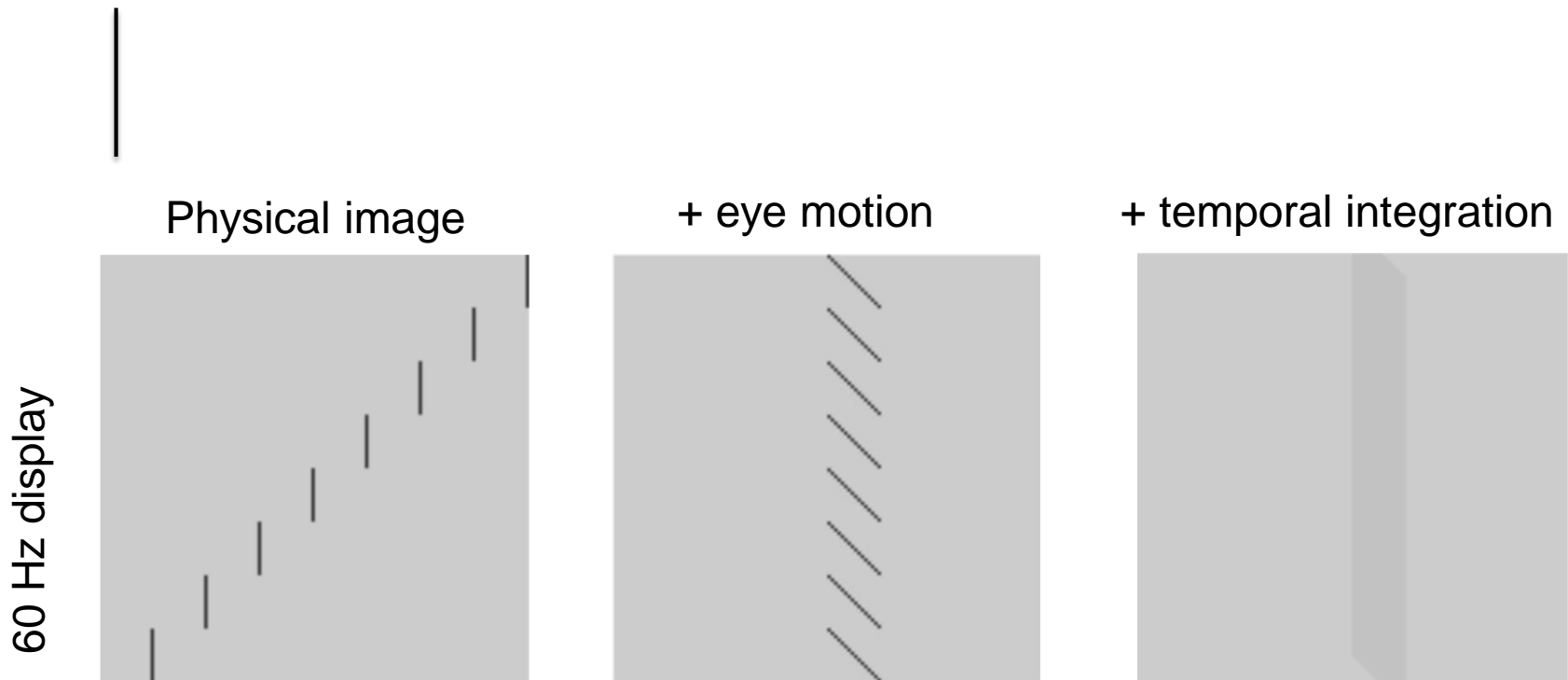
- ▶ The eye smoothly follows a moving object
- ▶ But the image on the display is “frozen” for  $1/60^{\text{th}}$  of a second



# Hold-on blur

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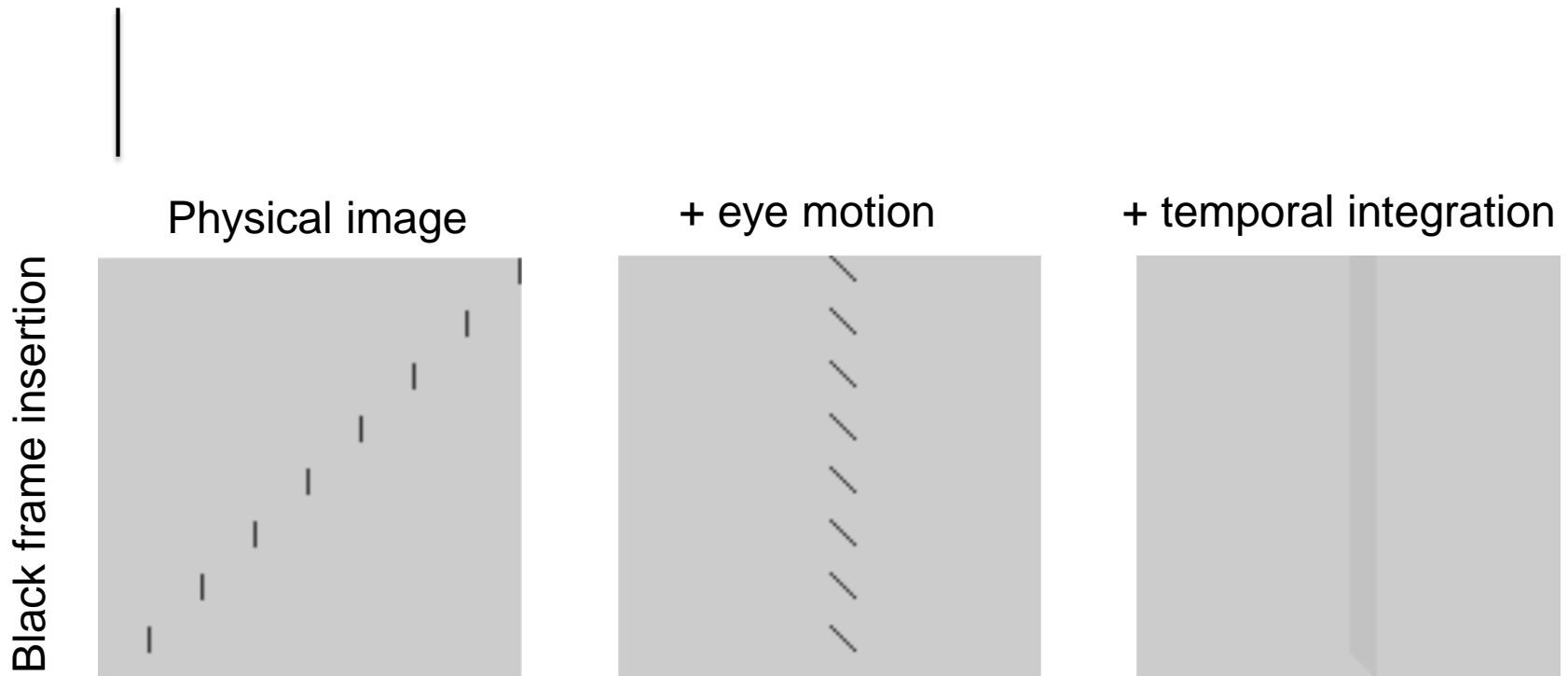
- ▶ The eye smoothly follows a moving object
- ▶ But the image on the display is “frozen” for  $1/60^{\text{th}}$  of a second





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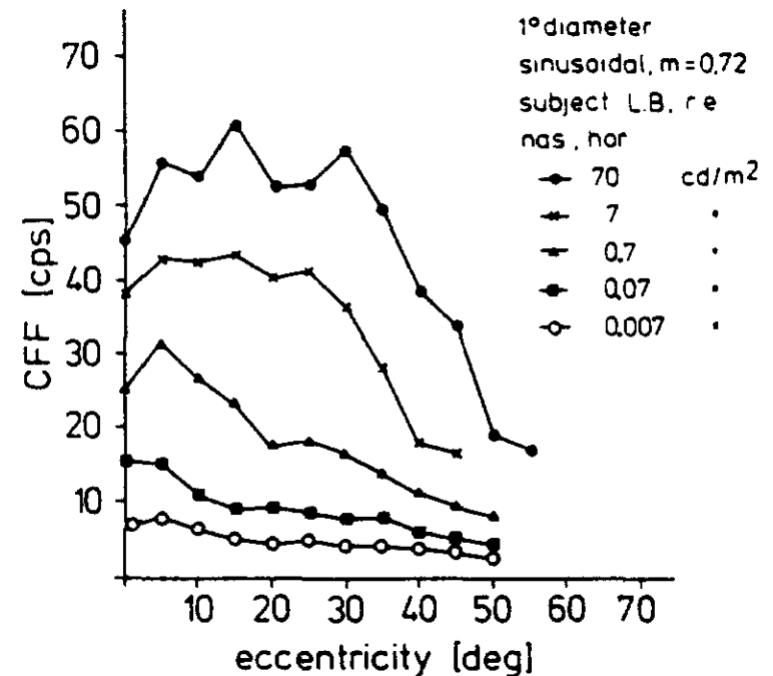
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# Flicker

## ▶ Critical Flicker Frequency

- ▶ Strongly depends on luminance – big issue for HDR VR headsets
- ▶ Increases with eccentricity
- ▶ and stimulus size
- ▶ It is possible to detect flicker even at 2kHz
  - ▶ For saccadic eye motion



[Hartmann et al. 1979]

# Simulation sickness

- ▶ Conflict between vestibular and visual systems
  - ▶ When camera motion inconsistent with head motion
  - ▶ Frame of reference (e.g. cockpit) helps
  - ▶ Worse with larger FOV
  - ▶ Worse with high luminance and flicker



# Summary

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- ▶ **HDR for VR is a great idea because**
  - ▶ It gives more realistic experience
  - ▶ Better quality with the same number of pixels
  - ▶ Additional depth cues
- ▶ **HDR for VR is bad idea because**
  - ▶ Increased flicker visibility
  - ▶ Increased simulation sickness
  - ▶ Lens glare will reduce effective dynamic range
- ▶ **In both cases**
  - ▶ Tone-mapping will become an important part of VR rendering

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  - ▶ Hainich, R. R., & Bimber, O. (2011). *Displays: Fundamentals and Applications*. CRC Press.
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  - ▶ [http://www.cl.cam.ac.uk/teaching/1718/AdvGraph/06\\_HDR\\_and\\_tone\\_mapping.pdf](http://www.cl.cam.ac.uk/teaching/1718/AdvGraph/06_HDR_and_tone_mapping.pdf)
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